

09:00 - 09:05	<b>Welcome</b>
09:05 - 09:35	<b>Norbert Krüger</b> , University of Southern Denmark, Odense Hierarchical structure of the human visual system
09:35 - 10:05	<b>Silvio Sabatini</b> , University of Genoa Deep representation hierarchies for 3D active vision
10:05 - 10:35	<b>Aleš Leonardis</b> , University of Birmingham Compositional hierarchies for scalable robot vision
10:35 - 10:55	Coffee break
10:55 - 11:25	<b>Michael Zillich</b> , Technical University Vienna Perceptual Grouping in RGB-D for Semantically Rich Visual Representations
11:25 - 11:55	<b>Tomohiro Shibata</b> , Kyushu Institute of Technology, Kitakyushu A hybrid direct feature matching based on-line loop-closure detection algorithm for topological mapping
11:55 - 12:25	<b>Mario Fritz</b> , Max Planck Institute for Informatics, Saarbrücken Scalable learning and perception
12:25 - 14:00	Lunch
14:00 - 14:30	<b>Francesca Odone</b> , University of Genoa Teaching iCub to see its world
14:30 - 15:00	<b>Aaron Bobick</b> , Georgia Tech, Atlanta Structured representations of human robot collaborative action
15:00 - 15:30	<b>Tamim Asfour</b> , Karlsruhe Institute of Technology Active visual perception for humanoid robots
15:30 - 15:50	Coffee break
15:50 - 16:20	<b>Kostas Daniilidis</b> , University of Pennsylvania, Philadelphia Active vision revisited
16:20 - 16:50	<b>Manuel Lopes</b> , INRIA, Bordeaux Learning Tasks and Representations from Human-Machine Interactions
16:50 - 17:10	<b>Aleš Ude</b> , Jožef Stefan Institute, Ljubljana Active visual learning on a humanoid robot
17:10 - 17:30	<b>Discussion</b>